

ABB DRIVES FOR WATER

ACQ580-04 R10 and R11 drives Quick installation guide





List of related manuals in English

Drive hardware manuals and guides	Code (English)
ACQ580-04 drive modules (200 to 500 kW) hardware manual	3AXD50000048677
ACQ580-04 drive modules (200 to 500 kW) quick	3AXD50000048678
installation guide	
ACX-AP-x Assistant control panels user's manual	3AUA0000085685
Drive firmware manuals	
ACQ580 pump control program firmware manual	3AXD50000035867
ACQ580 drives with pump control program quick start-up guide	3AXD50000048773
Option manuals and guides	
DPMP-02/03 mounting platform for control panels installation guide	e 3AUA0000136205
DPMP-06/07 mounting platform for control panels installation guide	e 3AXD50000289561
Manuals and quick guides for I/O extension modules, fieldbus	
adapters, etc.	
CCA-01 communication adapter quick guide	3AXD50000018457
CPTC-02 ATEX-certified thermistor protection module, Ex II (2) GD	3AXD50000030058
(+L537+Q971) user's manual	
FDNA-01 DeviceNet™ adapter module user's manual	3AFE68573360
FEIP-21 EtherNet/IP fieldbus adapter module User's manual	3AXD50000158621
FENA-01/-11/-21 Ethernet adapter module user's manual	3AUA0000093568
FMBT-21 Modbus/TCP Adapter Module User's Manual	3AXD50000158607
FPBA-01 PROFIBUS DP adapter module user's manual	3AFE68573271
FPNO-21 PROFINET IO fieldbus adapter module user's manual	3AXD50000158614
FSCA-01 RS-485 adapter module user's manual	3AUA0000109533
FOCH du/dt filters hardware manual	3AFE68577519
Flange mounting kit quick installation guide for ACX580-01 frames R0 to R5	3AXD50000036610
Flange mounting kit quick installation guide for ACQ580-01 frames	3AXD50000019099
R6 to R9	24VD5000040400
Flange mounting kit installation supplement	3AXD50000019100
Tool and maintenance manuals and guides	
Drive composer PC tool user's manual	3AUA0000094606
Converter module capacitor reforming instructions	3BFE64059629
NETA-21 remote monitoring tool user's manual	3AUA0000096939

You can find manuals and other product documents in PDF format on the Internet. See section *Document library on the Internet* on the inside of the back cover. For manuals not available in the Document library, contact your local ABB representative.

3AUA0000096881

The code below opens an online listing of the manuals applicable to this product.



ACQ580-04 manuals

NETA-21 remote monitoring tool installation and startup guide

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Quick installation guide

Contents of this guide

This guide tells you briefly how to install the drive module into a 600 mm wide cabinet. For installation examples in different cabinets and more detailed instructions, engineering guide lines, technical data and complete safety instructions, see the hardware manual (www.abb.com/drives: Select Document Library and search for document number 3AXD50000048677 [English]).

Obey the safety instructions

See figure A on page 13. If you ignore these instructions, injury or death, or damage to the equipment can occur.

WARNING! Handle the drive module carefully. Open the support legs by pressing each leg a little down and turning it aside (1, 2).

Do not tilt the drive module. It is **heavy** and its **center of gravity is high**. The module will overturn from a sideways tilt of 5 degrees. Do not leave the module unattended on a sloping floor.

To prevent the drive module from falling, attach its top lifting lugs with chains to the cabinet frame before you push the module into the cabinet. Work carefully preferably with help from another person. Keep a constant pressure with one foot on the base of the module to prevent the module from falling on its back.



WARNING! If you are not a qualified electrician, do not do installation or maintenance work. Go through these steps before you begin any installation or maintenance work.

- 1. Clearly identify the work location.
- Disconnect all possible voltage sources.
 - Open the main disconnecter of the drive.
 - Open the disconnecter of the supply transformer as the main disconnecter of the drive does not remove the voltage from the input busbars of the drive.
 - Make sure that reconnection is not possible. Lock the disconnecters to open position and attach a warning notice to them.
 - Disconnect any external power sources from the control circuits before you
 do work on the control cables.
 - After you disconnect the drive, always wait for 5 minutes to let the intermediate circuit capacitors discharge before you continue.
- 3. Protect any other energized parts in the work location against contact.
- 4. Take special precautions when close to bare conductors.
- Measure that the installation is de-energized.
 - Use a multimeter with an impedance of at least 1 Mohm.

- Make sure that the voltage between the drive module input power terminals (L1/U1, L2/V1, L3/W1) and the grounding (PE) busbar is close to 0 V.
- Make sure that the voltage between the drive module UDC+ and UDCterminals and the grounding (PE) busbar is close to 0 V.
- Install temporary grounding as required by the local regulations. 6.
- 7. Ask for a permit to work from the person in control of the electrical installation work.

Select the power cables

Size the power cables according to local regulations to carry the nominal current given on the type designation label of your drive.

Ensure the cooling and fuses (UL)

See the table below for the losses and cooling air flow through the drive. The allowed operating temperature range of the drive without derating is -15 to +40 °C.

Drive type	Air flow	Heat dissipation	UL class	Fuse
Drive type	ft ³ /min	W	UL Class	Type
ACQ580-505A-4	707	5602	Т	JJS-600
ACQ580-585A-4	707	6409	L	A4BY800
ACQ580-650A-4	707	8122	L	A4BY800
ACQ580-725A-4	707	8764	L	A4BY800
ACQ580-820A-4	707	9862	L	A4BY900
ACQ580-880A-4	848	10578	L	A4BY1000

For more information, see the hardware manual 3AXD5000004867748677 (English).

Protect the drive and input power cables

See the table above for the UL class fuses for branch circuit protection per NEC. Check that the operating time of the fuse is below 0.1 seconds. Obey local regulations.

Install the drive module into a cabinet

See figure B on page 13:

- Install the punched section to the back of the cabinet frame.
- Remove the pedestal guide plate from the bottom of the drive module.
- Install the support rails and pedestal guide plate to the cabinet bottom frame.
- Install the telescopic insertion ramp to the pedestal guide plate.

For option +B051: See figure C on page 13:

Remove the sheeting from the clear plastic shrouds from both sides.

See figure D on page 13:

- Install the mounting bracket to the drive module.
- For option +B051:
 - Install the bottom grille to the drive module if there is no bottom plate in the cabinet and degree of protection of IP20 is needed for the drive module from the bottom side.

- Install the top metallic shroud to the drive module.
- Install the back shrouds to the drive module.

See figure E on page 13:

- Attach the drive module to the cabinet frame with chains.
- Push the drive module into the cabinet along the telescopic insertion ramp.
- Remove the ramp.

See figure F on page 13:

- Attach the drive module to the pedestal guide plate.
- Attach the drive module from top to the punched section at the cabinet back.
 Note: The mounting bracket grounds the drive module to the cabinet frame.

Check the insulation of the input and motor cables and the motor

Check the insulation of the input cable according to local regulations before you connect it to the drive.

See figure H on page 14. Ground the motor cable shield at the motor end. For minimal interference, make a 360-degree grounding at the cable lead-through, or keep the pig tail short

Check the insulation of the motor and motor cable when the motor cable is disconnected from the drive, see figure I on page 14. Measure the insulation resistance between each phase conductor and then between each phase conductor and the Protective Earth conductor using a measuring voltage of 1000 V DC. The insulation resistance of an ABB motor must exceed 100 Mohm (reference value at 25 °C or 77 °F). For the insulation resistance of other motors, consult the manufacturer's instructions. **Note:** Moisture inside the motor casing will reduce the insulation resistance. If you suspect moisture, dry the motor and repeat the measurement

Connect the power cables (and install the shrouds for option +B051)

See figure G on page 14.

Step	Task (motor cables)	Figure	Page
1	Install the grounding terminal to the drive module base.	J	14
2	Run the motor cables to the cabinet. Ground the cable shields 360 degrees at the cabinet lead-through.	К	14
3	Connect the twisted shields of the motor cables to the grounding terminal.	L	14
4	Install the T3/W2 connection terminal to the insulators. WARNING! Do not use longer screws or bigger tightening torque than given in the installation drawing. They can damage the insulator and cause dangerous voltage to be present at the module frame.	М	14
5	Connect the phase conductors to the T3/W2 terminal.	N	14
6	Install the T2/V2 connection terminal to the insulators. See the warning in step 4.	-	-
7	Connect the phase conductors to the T2/V2 connection terminal.	-	-
8	Install the T1/U2 connection terminal to the insulators. See the warning in step 4.		-
9	Connect the phase conductors to the T1/U2 terminal.	-	-
10	For option +B051 (if there is no bottom plate in the cabinet and degree of protection of IP20 is needed): • Step drill carefully sufficiently big holes to the inner clear plastic shrouds for the motor cables to the connected. Smooth the hole edges. Cut the shroud from the holes to the edge to make it possible to put the shroud around the cables. • Remove the plastic sheeting from the shrouds from both sides.	0	15
11	For option +B051: Put the inner clear plastic shrouds of figure O around the motor cables.		15
12	For option +B051: Remove the plastic sheeting from the output clear plastic shroud from both sides. Install the shroud to the drive module.		15
13	For option +B051: Install the lower front cover to the drive module.	Q	15

Step	Task (input cables)		Page
1	Ground the input cable shields (if present) 360 degrees at the cabinet lead-through.	-	-
2	Connect the twisted shields of the input cables and separate ground cable (if present) to the cabinet grounding busbar.	-	-

Step	Task (input cables)	Figure	Page
3	 For option +B051: Step drill carefully sufficiently big holes to the lead-through clear plastic shroud for the cables to the connected. Align the holes in the vertical direction according to the alignment holes in the shroud. Smooth the hole edges. Remove the plastic sheeting from both sides of the shroud. Attach the cables firmly to the cabinet frame to prevent chafing against the hole edges. 	R	15
4	For option +B051: Put the conductors of the input cables through the drilled holes in the clear plastic shroud.	S	15
5	Connect the input power cable conductors to the L1/U1, L2/V1 and L3/W1 connection busbars.	Т	15
6	For option +B051: Move the lead-through clear plastic shroud along input cables to its final position. Install the front clear plastic shroud.	U	16
7	Install the upper front cover.	U	16
8	Remove the cardboard protective covering from the drive module air outlet.	U	16
9	For option +B051: Cut the hole for the lead-through clear plastic shroud in the side clear plastic shroud. Install the side and top clear plastic shrouds to the drive module.	V	16

Install the air baffles

See figure W on page 16 and *Guidelines for planning the cabinet installation* in the hardware manual.

Connect the control cables

See figure X on page 16.

- Ground the outer shields of all external control cables 360 degrees at the cabinet lead-through.
- Ground the pair-cable shields of external control cables to a grounding clamp below the control unit. Leave the other end of the shields unconnected or ground them indirectly via a high-frequency capacitor with a few nanofarads, eg, 3.3 nF / 630 V.
- Connect the conductors to the appropriate terminals of the control unit. See page 10.
- 4. Wire the optional modules if included in the delivery.

Default I/O connections

Default I/O connections are shown below.

X1 Reference voltage and analog inputs and outputs					
<i></i>	1 SCR Signal cable shield (screen)				
		2	Al1	Output frequency/speed reference: 010 V	
	* 	3	AGND	Analog input circuit common	
		4	+10V	Reference voltage 10 V DC	
		5	Al2	Not configured	
		6	AGND	Analog input circuit common	
	•	7	AO1	Output frequency: 020 mA	
		8	AO2	Output current: 020 mA	
		9	AGND	Analog output circuit common	
	• -	X2 & X3		output and programmable digital inputs	
		10	+24V	Aux. voltage output +24 V DC, max. 250 mA	
	 	11	DGND	Aux. voltage output common	
		12	DCOM	Digital input common for all	
	 	13	DI1	Stop (0) / Start (1)	
		14	DI2	Forward (0) / Reverse (1)	
	<u> </u>	15	DI3	Constant frequency/speed selection	
16		16	DI4	Constant frequency/speed selection	
17			DI5	Ramp set 1 (0) / Ramp set 2 (1)	
		18	DI6	Not configured	
		X6, X7, X8	Relay outputs		
		19	RO1C	Ready run	
	74	20	RO1A	250 V AC / 30 V DC	
_	 	21	RO1B	—	
		22	RO2C	Running	
	1/2	23	RO2A	250 V AC / 30 V DC	
_	+4 $ -$	24	RO2B		
		25	RO3C	Fault (-1)	
	14	26	RO3A	250 V AC / 30 V DC	
	+	27	RO3B	→	
	· 	X5	EIA-485 Modb	ous RTU	
		29	B+		
		30	A-	Embedded Modbus RTU (EIA-485)	
		31	DGND		
S4		TERM	Serial data link termination switch		
S5			BIAS	Serial data link bias resistors switch	
		X4	Safe torque of		
		34	OUT1	Safe torque off. Factory connection. Both circuits	
		35	OUT2	must be closed for the drive to start. See chapter	
		36	SGND	The Safe torque off function in ACQ580-01 (0.75	
		37	IN1 IN2	to 250 kW, 1.0 to 350 hp) hardware manual	
	38			(3AXD50000048677[English]).	

Total load capacity of the Auxiliary voltage output +24V (X2:10) is 6.0 W (250 mA / 24 V DC). Wire sizes:

0.2...2.5 mm² (24...14 AWG): Terminals +24V, DGND, DCOM, B+, A-, DGND, Ext. 24V 0.14...1.5 mm² (26...16 AWG): Terminals DI, AI, AO, AGND, RO, STO

Tightening torques: 0.5...0.6 N·m (0.4 lbf·ft)

Total load capacity of the Auxiliary voltage output +24V (X2:10) is 6.0 W (250 mA / 24 V DC).

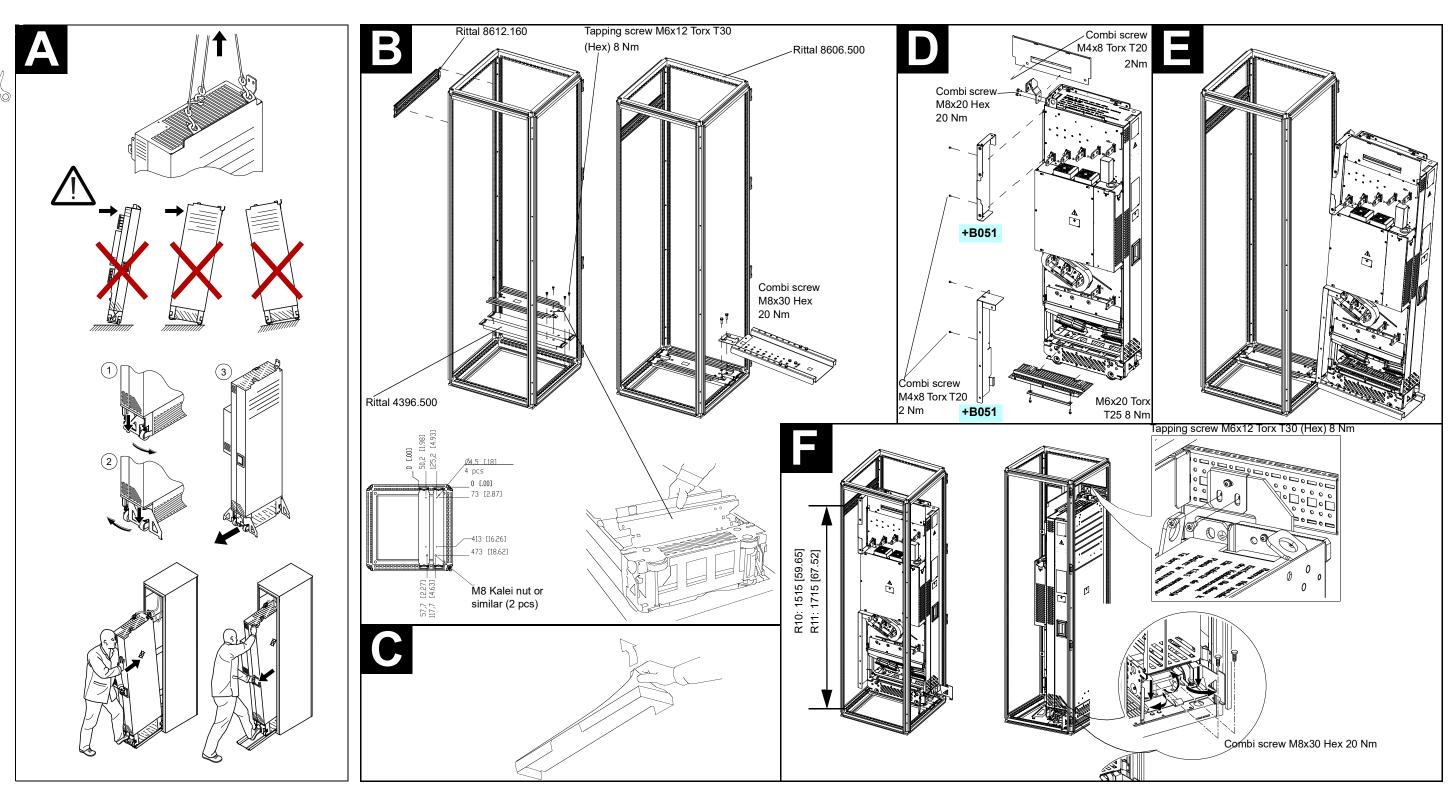
Wire sizes: 0.14...2.5 mm² (26...16 AWG): All terminals

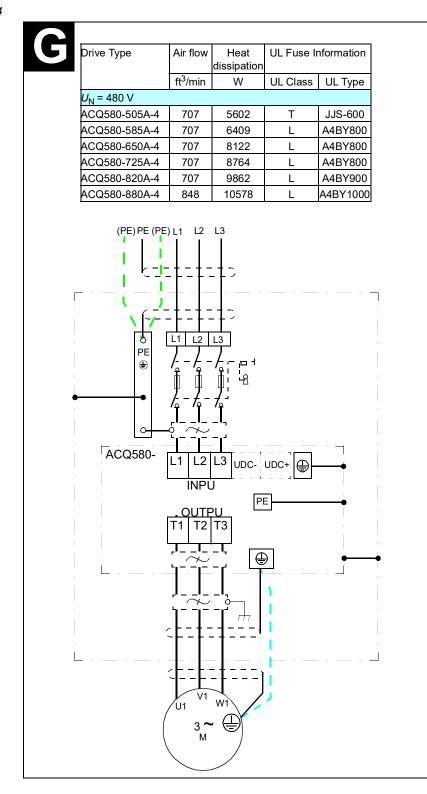
Tightening torques: 0.5...0.6 N·m (0.4 lbf·ft)

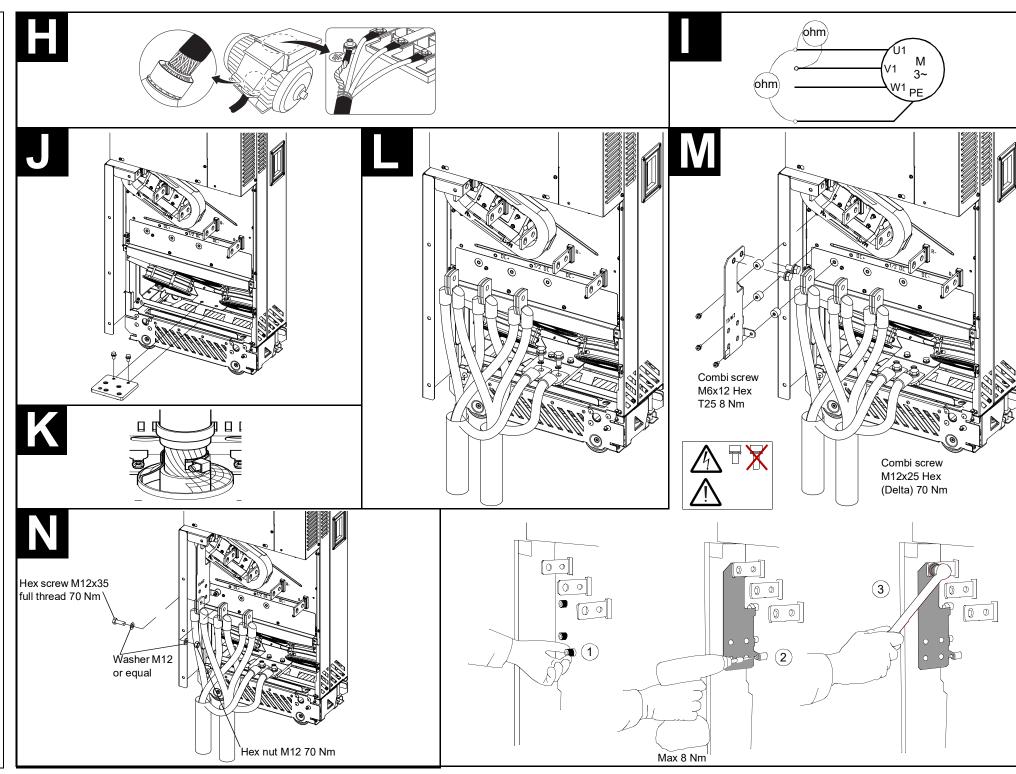
UL checklist

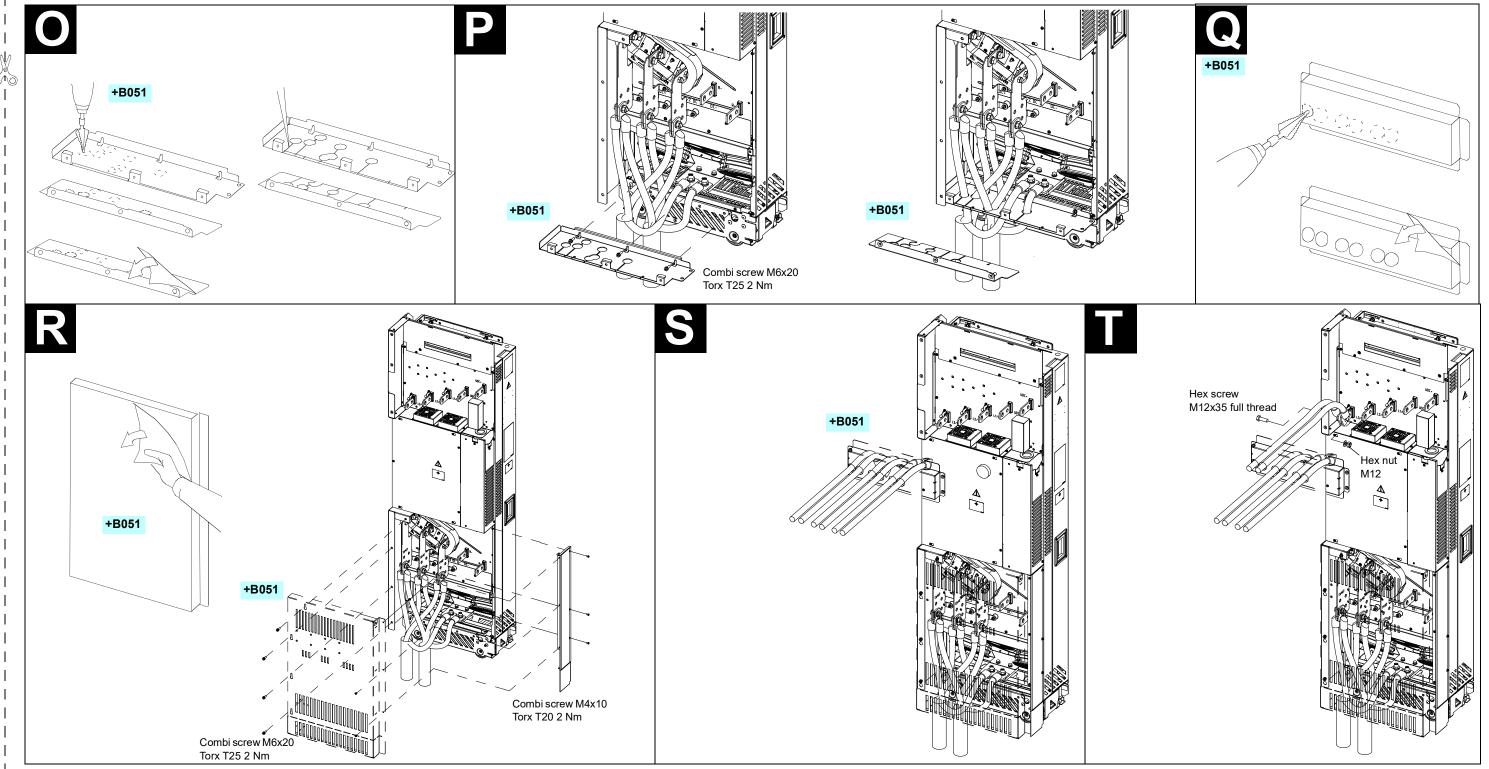
- The drive must be installed in clean air according to enclosure classification.
 Cooling air must be clean, free from corrosive materials and electrically conductive dust.
- The maximum ambient air temperature is 40 °C (104 °F) at rated current. The current is derated for 40 to 55 °C (104 to 131 °F).
- The drive is suitable for use in a circuit capable of delivering not more than 100,000 rms symmetrical amperes, 600 V maximum. The ampere rating is based on tests done according to UL 61800-5-1.
- The cables located within the motor circuit must be rated for at least 75 °C (167 °F) in UL-compliant installations.
- The input cable must be protected with fuses. Circuit breakers must not be used without fuses in the USA. Suitable IEC (class aR) fuses and UL (class T) fuses are listed in the hardware manual. For suitable circuit breakers, contact your local ABB representative.
- For installation in the United States, branch circuit protection must be provided in accordance with the National Electrical Code (NEC) and any applicable local codes. To fulfill this requirement, use the UL classified fuses.
- For installation in Canada, branch circuit protection must be provided in accordance with the Canadian Electrical Code and any applicable provincial codes. To fulfill this requirement, use the UL classified fuses.
- The drive provides overload protection in accordance with the National Electrical Code (NEC).

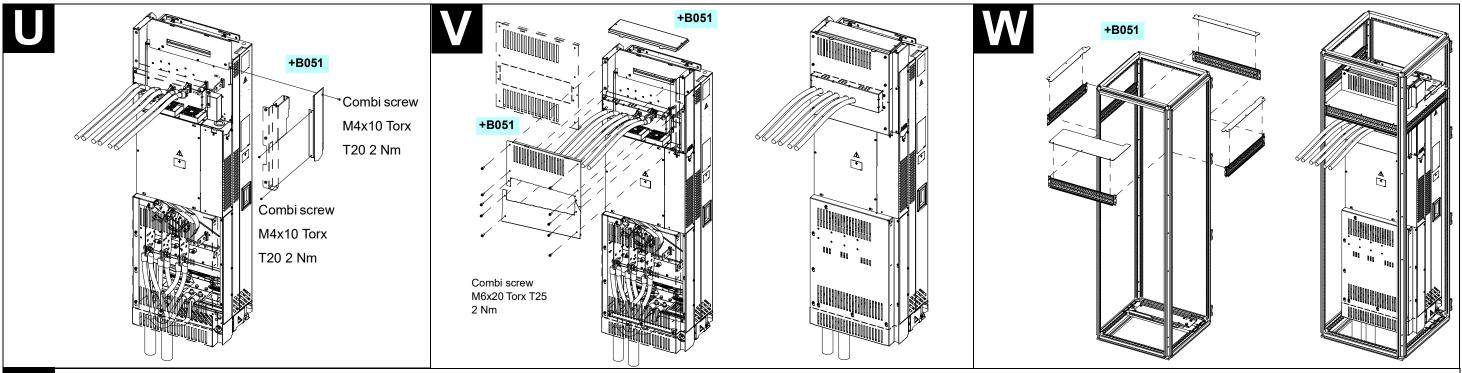
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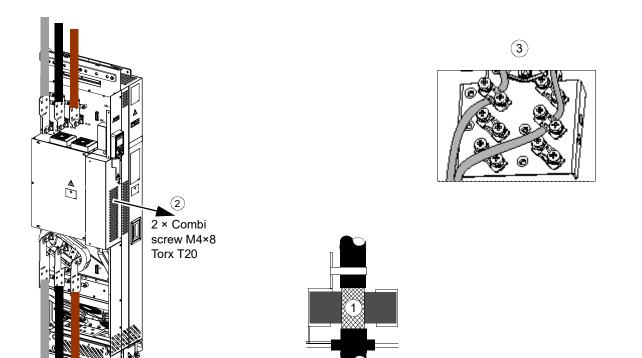




ABB DRIVES FOR WATER

Quick start-up guideBasic ACQ580 program setup



Quick start-up guide

This guide describes how to start-up the drive using the First start assistant on the Hand-Off-Auto control panel. For complete information on start-up, see *ACQ580 firmware manual* (3AXD50000035867 [English]).

Before you start

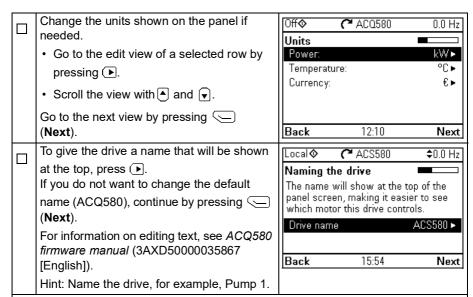
Ensure that the drive has been installed as described in

Start-up with the First start assistant on a Hand-Off-Auto control panel

Safety

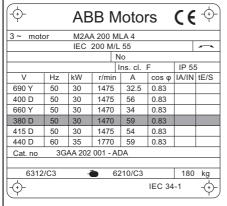
Make sure that the installation work is complete. Make sure that cover of the drive and the cable box, if included, are on place. Check that the starting of the motor does not cause any danger. Decouple the driven machine if there is a risk of damage in case of an incorrect direction of rotation. Hints on using the assistant control panel The two commands at the bottom of the display (Options and Menu in the figure on the right), show the functions of the two softkeys and located below the display. The commands assigned to the softkeys vary depending on the context. Use keys ✓, ♠, ♠ and ✓ to move the cursor and/or change values depending on the active view. Key ? shows a context-sensitive help page. 1 − First start assistant guided settings: Language, date and time, and motor nominal values Have the motor or pump name plate data at hand. Power up the drive.						
Couple the driven machine if there is a risk of damage in case of an incorrect direction of rotation. Hints on using the assistant control panel The two commands at the bottom of the display (Options and Menu in the figure on the right), show the functions of the two softkeys → and → located below the display. The commands assigned to the softkeys vary depending on the context. Use keys → , ▶ , ♠ and ▼ to move the cursor and/or change values depending on the active view. Key ? shows a context-sensitive help page. 1 − First start assistant guided settings: Language, date and time, and motor nominal values Have the motor or pump name plate data at hand.						
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display (Options and Menu in the figure on the right), show the functions of the two softkeys and located below the display. The commands assigned to the softkeys vary depending on the context. Use keys ♠, ♠, ♠ and ♦ to move the cursor and/or change values depending on the active view. Key ? shows a context-sensitive help page. 1 - First start assistant guided settings: Language, date and time, and motor nominal values Have the motor or pump name plate data at hand.	Hints on using the assistar	nt control panel				
Language, date and time, and motor nominal values Have the motor or pump name plate data at hand.	The two commands at the bottom of the display (Options and Menu in the figure on the right), show the functions of the two softkeys and located below the display. The commands assigned to the softkeys vary depending on the context. Use keys , , , and to move the cursor and/or change values depending on the active view.					
Have the motor or pump name plate data at hand.						
hand.						
Power up the drive.	· · · ·					
	Power up the drive.					

	The First start assistant guides you through the first start-up.	English Deutsch
	The assistant begins automatically. Wait	Suomi
	until the control panel enters the view shown	Français
	on the right.	Italiano
	Select the language you want to use by	Nederlands Svenska
	highlighting it (if not already highlighted) and	I
	pressing (OK).	0K ►
	Note: After you have selected the language, it takes a few minutes for the control panel to wake up.	
	Select Start set-up and press (Next).	Off♦ (~ ACQ580 0.0 Hz
		Set up assistant
		Set up drive now?
		Start set-up
		Exit & don't show at power-up Not now
		1400 110 00
		13:23 Next
	Set the date and time as well as date and	Local ♦ (~ ACS580
	time display formats.	Date & time
	Go to the edit view of a selected row by	Please enter the current date and time.
	pressing •.	Date 04.07.2014 ►
	 Scroll the view with ♠ and ♠. 	Time
	9 _	Show date as day.month.year ► Show time as 24-hour ►
	Go to the next view by pressing (Next).	Back 15:54 Next
	To change a value in an edit view:	Local ♦ (* ACS580 \$ 0.0 Hz
Ш	Use	Date
	and right.	Day Month Year
	• Use ▲ and 🗨 to change the value.	04 .07.2014
	• Press (Save) to accept the new	Friday
	setting, or press (Cancel) to go	0 1 1554
	back to the previous view without making changes.	Cancel 15:54 Save

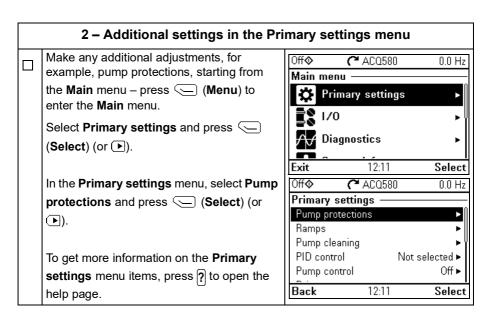


Refer to the motor or pump nameplate for the following nominal value settings of the motor. Enter the values <u>exactly</u> as shown on the motor or pump nameplate.

Example of a nameplate of an induction (asynchronous) motor:



Ιп	Check that the motor data is correct. Values	Local♦	C ACS580	\$0.0 Hz
	are predefined on the basis of the drive size but you should verify that they correspond to the motor.		minal values	
			Find the values on the motor's	
		· ·	e, and enter then	
	Start with the motor type.Go to the edit view	Type: Current:	Asynchro	nous motor► 1.8 A►
	of a selected row by pressing 🕩.	Voltage:		400.0 V ►
	 Scroll the view with	Back	15:56	
	Motor nominal cosΦ and nominal torque are	раск	10.00	Next
	optional.			
	Press (Next) to continue.			
	Adjust the limits according to your needs.	TOCC A	5	
		Off �	(~ ACQ580	0.0 Hz
	Go to the edit view of a selected row by	Limits		
	pressing 💽.		e allowed operati i frequency	on range: 0.00 Hz ►
	 Scroll the view with ▲ and ▼. 		n frequency	50.00 Hz ►
	Go to the next view by pressing			00.00 1.2
	(Next).			
		Back	12:10	Next
	If you want to make a backup of the settings	Off♦	(~ ACQ580	0.011-
	made so far, select Backup and press			0.0 Hz
	(Next).	Make ba	скир: settings into a b	ackun file
	If you do not want to make a backup, select	stored in	the control pane	l. To restore
	Not now and press (Next).		, go to Menu ≻ B	lackups.
	Not now and press (Next).	Backup Not now		
		Back	12:10	Next
П	The first start is now complete and the drive	Off 	(~ ACQ580	0.0 Hz
	is ready for use.	First sta	rt complete	
	Press (Done) to enter the Home view.	The drive	is ready to run t	he motor.
		Press "A control.	uto" to świtch to	external
		Start/Sto	nn:	DI1
		Referenc		Al1 scaled
		Back	12:11	Done
-	The Hame view monitoring the values of the			
	The Home view monitoring the values of the selected signals is shown on the panel.	Off�	(~ ACQ580	0.0 Hz
	science signals is shown on the parior.	Output f	requency	0.00
	For changing the signals and their display	M otor c	urrent	0.00▶
	style shown in the Home view, see ACQ-AP-	\ A		0.00
	x assistant control panels user's manual (3AUA0000085685 [English]).	Motor to	orque	0.0
	(SACAGGGGGGGGGGGGGGGGGGGGGGGGGGGGGGGGGGG	(,,	12:11	Menu
1				



3 - Hand/Off/Auto operation

The drive can be in remote control or local control, and in local control there are additionally two different modes.

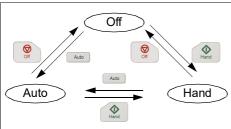
Remote control: Drive is controlled from the I/O or the fieldbus.

• Top row of the view shows Auto.

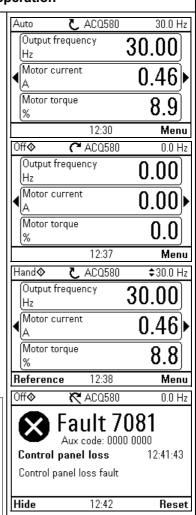
Local control: Drive is controlled from the control panel.

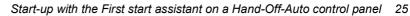
- Top row of the view shows Off, that is, the drive is in the Off mode. Drive is stopped.
- Top row of the view shows Hand, that is, the drive is in the Hand mode. Drive is running. The initial reference in the Hand mode is copied from the drive reference. Symbol ♦ on the top row indicates that you can change the reference with [A] and 🔻.

The following diagram shows the state transitions when you press the Hand, Off or Auto button:



Note: When you restart the drive while fault 7081 Control panel loss is active, the mode changes from Hand or Off to Auto.





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Further information

Product and service inquiries

Address any inquiries about the product to your local ABB representative, quoting the type designation and serial number of the unit in question. A listing of ABB sales, support and service contacts can be found by navigating to www.abb.com/searchchannels.

Product training

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